

<b>SEMESTER</b> <i>Sixth</i>	<b>DEPARTMENT</b> <i>Control Engineering</i>	<b>COURSE TITLE</b> <i>Control Theory II</i>
<b>COURSE CODE</b> <i>EC606</i>	<b>HOURS: 3</b> <b>UNITS: 3</b>	<b>COURSE SPECIFICATIONS</b> <i>Theoretical Contents</i>
<b>1. Introduction to Digital Control.</b> <ul style="list-style-type: none"> <li>➤ Discrete-time simulation with Simulink.</li> <li>➤ Time-domain controller emulation.</li> <li>➤ Frequency-domain controller emulation</li> </ul>		
<b>2. Digital Effects</b> <ul style="list-style-type: none"> <li>➤ Sampling, aliasing, zero-order hold.</li> <li>➤ Discrete-time plant modeling.</li> <li>➤ Filter structure and finite-precision effects.</li> </ul>		
<b>3. State-Space Controller Design</b> <ul style="list-style-type: none"> <li>➤ State-feedback controller design.</li> <li>➤ 11. State estimation and control design.</li> </ul>		
<b>4. Transfer Function Controller Design:</b> <ul style="list-style-type: none"> <li>➤ Frequency-response controller design.</li> <li>➤ Numeric optimal PID controller design</li> </ul>		
<b>References:</b> <ol style="list-style-type: none"> <li>1. K. Ogata, "Discrete Time Control Systems, 2<sup>nd</sup> ed.", Prentice Hall, 1995.</li> <li>2. B.C. Kuo, "Digital Control Systems, 2<sup>nd</sup> ed.", Oxford Univ. Press, 1992.</li> <li>3. G.F. Franklin, J.D. Powell and M. Workman, "Digital Control of Dynamic Systems, 3<sup>rd</sup> ed." Addison-Wesley Publisher, 2006.</li> </ol>		